# **Digital Control Theory**

#### 2 units (selection)

**Target**> This class introduces the fundamental concept of digital control and neural network that can be used to design the optimal control systems based on the modern control theory.

**Outline**> In this lecture the fundamental conception of a digital control system and digital control strategies to apply the modern control theory is presented. In particular, two freedom control and a neural network is explained. The recent topics related to control engineering are also introduced.

## Style > Lecture

Keyword > two freedom control, neural network, optimal control

**Fundamental Lecture**> "Automatic Control theory 1"(1.0), "Automatic Control theory 2"(1.0)

## **Relational Lecture** (0.5) **"Actuator Control Theory**"

**Requirement**> Students are required to have a good understanding of undergraduatelevel control theory and related subjects.

#### Goal

**1.** To understand the outline of the digital control.

2. To understand the applications of AI, neural network and fuzzy control

### $\textbf{Schedule}\rangle$

1. Outline of digital control system

2. Difference of analog and digital control systems

**3.** Mathematical representation of control signal

- 4. Pulse transfer function
- 5. Stability and steady state deviation
- **6.** Design of digital control system(PID)
- 7. Design of digital control system(two freedom control)
- **8.** Design of digital control system(model prediction)
- 9. Intermediate examination
- **10.** Outline of artificial intelligence
- **11.** Exercise of artificial intelligence
- 12. Outline of neural network
- **13.** Exercise of neural network
- 14. Outline of fuzzy theory
- **15.** Exercise of fuzzy theory

- **16.** Final examination
- Evaluation Criteria evaluate based on two examinations and reports.

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- **Textbook** To be introduced in the class
- **Reference**> To be introduced in the class

Contents http://cms.db.tokushima-u.ac.jp/cgi-bin/toURL?EID=216774

**Student**> Able to be taken by only specified class(es)

#### **Contact**>

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